# ON THE COMBINED EFFECT OF A WEDGE AND 

## STAMP ON AN ELASTIC HALF-PLANE

## ( O sovmestivo deisivil na upruauty POLUPLOSKOAT' KLINA I SHTAMPA)

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\begin{aligned}
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\end{aligned}
$$

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1. Fundamental dependenoes. Let us start from the following easily verifled representation of the solution of the equilibrium equations of the plane theory of elasticity in displacements:

$$
\begin{align*}
& 2 \mu u=\operatorname{Re}\left[x_{0} \Phi+i y \Phi^{\prime}+\left(1+x_{0}\right) \Psi-x \Psi^{\prime}\right]  \tag{1.1}\\
& 2 \mu v=-\operatorname{Re}\left[\left(1+x_{0}\right) \Phi-i y \Phi^{\prime}+x_{0} \Psi+x \Psi^{\prime}\right] i \quad\left(x_{0}=\frac{\mu}{\lambda+\mu}\right)
\end{align*}
$$

Here $\Phi, \Psi$ are arbitrary analytic functions of the complex variable $z=x+t y$, defined in the domain of a section of the body or plate. The solution (1.1) may be found by superposition of the first and second solutions and discarding excess functions [1]. We obtain

$$
\begin{gather*}
\sigma_{x}=\operatorname{Re}\left[\Phi^{\prime}+i y \Phi^{\prime \prime}+\Psi^{\prime}-x \Psi^{\prime \prime}\right] \\
\sigma_{y}=\operatorname{Re}\left[\Phi^{\prime}-i y \Phi^{\prime \prime}+\Psi^{\prime}+x \Psi^{\prime \prime}\right]  \tag{1.2}\\
\tau_{x y}=-\operatorname{Re}\left[y \Phi^{\prime \prime}+i x \Psi^{\prime \prime}\right]
\end{gather*}
$$

The relationships
hold.

$$
\begin{align*}
& 2 \mu \frac{\partial v}{\partial x}=-\left(1+x_{0}\right) \operatorname{Re} i\left(\Phi^{\prime}+\Psi^{\prime}\right)+\tau_{x y} \\
& 2 \mu \frac{\partial u}{\partial y}=\left(1+x_{0}\right) \operatorname{Re} i\left(\Phi^{\prime}+\Psi^{\prime}\right)+\tau_{x y} \tag{1.3}
\end{align*}
$$

2. Repretentation of the solution for half-plane. Let a smooth, thin, symmetric, absolutely stiff wedge of given shape be inserted on the portion $L_{x}$ along the $x$-axis in an elastic half-plane $x \geq 0$. Only a normal loading of intensity $-p(y)$ which is symmetric relative to the origin is applied on the half-plane boundary $x=0$. Because of the symmetry of the loading, the tangential stresses equal zero on the $x$-axis. Consequently, the elastic displacements of points in the direction of the $y$-axis equal zero on the $x$-axis outside the wedge.

The absence of tangential stresses at points of the $x$ - and $y$-axes leads to the conditions
$\operatorname{Re} i \Phi^{\prime}=0, \quad x=0,-\infty<y<\infty, \quad \operatorname{Re} i \Psi^{\prime}=0, \quad y=0, \quad 0<x<\infty$
Hence, it also follows from (1.3) that the function $\Phi^{\prime}(z)$ is continued analytically through the $y$-axis as well as through those portions of the $x$-axis where $\partial \nu / \partial x$ vanishes. Hence, the imaginary parts of $\Phi^{\prime}$ take values of opposite sign at points of the $x$-axis symmetric to the origin. On the basis of (2.1) and (1.3) we arrive at the problem: in the upper half-plane to find an analytic function $\Phi^{\prime}(z)$, which vanishes at infinity, according to the following condition on the two portions $L_{x}$ of the $x$-axis, which are symmetrically disposed relative to the origin:

$$
\begin{equation*}
\operatorname{Re} i \Phi^{\prime}=-q_{0} v_{x}^{\prime}, \quad q_{0}=\frac{2 \mu}{1+x_{0}} \tag{2.2}
\end{equation*}
$$

We write its solution as

$$
\begin{equation*}
\Phi^{\prime}(z)=\frac{2 q_{0}}{\pi} \int_{L_{x}} \frac{x v_{x}^{\prime} d x}{x^{2}-z^{2}} \tag{2.3}
\end{equation*}
$$

Here $L_{x}$ is the portion lying to the right of the origin. Conditions on the $y$-axis

$$
\begin{equation*}
\operatorname{Re} \Psi^{\prime}(z)=\sigma_{x}{ }^{\circ}(y), \quad \sigma_{x}{ }^{\circ}(-y)=\sigma_{x}{ }^{\circ}(y) \tag{2.4}
\end{equation*}
$$ follow from the properties of the function $\psi^{\prime}(z)$.

Hence

$$
\begin{equation*}
\Psi^{\prime}(z)=\frac{2 z}{\pi} \int_{0}^{\infty} \frac{\sigma_{x}^{0} d y}{y^{2}+z^{2}} \tag{2.5}
\end{equation*}
$$

On the $\boldsymbol{v}$-axis we have

$$
\begin{equation*}
\sigma_{x}=-p(y) \tag{2.6}
\end{equation*}
$$

Satisfying this boundary condition, we obtain

$$
\begin{equation*}
\frac{2 q_{0}}{\pi} \frac{d}{d y}\left(y \int_{L_{x}} \frac{x v_{x}^{\prime} d x}{x^{2}+y^{2}}\right)+\sigma_{x}^{\circ}=-p(y) \tag{2.7}
\end{equation*}
$$

Substituting the value of $\sigma_{\mathrm{x}}{ }^{\circ}$ into (2.5), we find after having taken an intermediate integral

$$
\begin{equation*}
\Psi^{\prime}(z)=-\frac{2 q_{0}}{\pi} \int_{L_{x}} \frac{x v_{x}^{\prime} d x}{(x+z)^{2}}-\frac{2 z}{\pi} \int_{0}^{\infty} \frac{p(y) d y}{y^{2}+z^{2}} \tag{2.8}
\end{equation*}
$$

For specified $v_{z}^{\prime}$ and $p(y)$, Formulas (2.3) and (2.8) yield the solution of the problem of a stiff wedge and an additional loading acting on a halfplane. For $p(\nu)=0$, in particular, we obtain the solution of the problem of cleavage of a half-plane without taking account of crack formation. This solution does not demand knowledge of the second derivative [l] of $v(x, 0)$. let us consider the following examples.

1. Parabolic wedge driven in along the $x$-axis to a depth $H$. On the wedge portion we have

$$
\begin{equation*}
v_{x}^{\prime}=-\frac{h}{2 \sqrt{H} \sqrt{H-x}} \tag{2.9}
\end{equation*}
$$

The derivative is $v_{x}^{\prime}=0$ outside this portion on the $x$-axis. We obtain $\Phi^{\prime}(z)=-\frac{h q_{0}}{\pi \sqrt{H}} \int_{0}^{H} \frac{x d x}{\sqrt{H-x}\left(x^{2}-z^{2}\right)}, \quad \Psi^{\prime \prime}(z)=\frac{h q_{0}}{\pi \sqrt{\bar{H}}} \int_{0}^{H} \frac{x d x}{\sqrt{H-x}(x+z)^{2}}$
or

$$
\begin{gather*}
\Phi^{\prime}(z)=-\frac{q_{0} h}{2 \pi H}\left[\chi\left(\xi_{1}\right)-\chi\left(\xi_{2}\right)\right], \quad \Psi^{\prime}(z)=\frac{q_{0} h}{\pi(H+z)}\left[\chi\left(\xi_{1}\right)-1\right]  \tag{2.11}\\
\chi(\xi)=\xi \ln \frac{1-\xi}{1+\xi}, \quad \xi_{1}^{2}=\frac{H}{H+z}, \quad \xi_{z^{2}}{ }^{2}=\frac{H-z}{H} \tag{2.10}
\end{gather*}
$$

2. A half-plane reinforced along the $x$-axis by a system of $m$ stiff, thin insertions of elliptic shape with semi-axes $h_{1}, \ell_{1}$. We obtain

$$
\begin{equation*}
v_{x j}^{\prime}=-\frac{h_{j}}{l_{j}}\left(x-H_{j}\right)\left[l_{j}^{2}-\left(x-H_{j}\right)^{2}\right]^{-1 / x} \tag{2.12}
\end{equation*}
$$

where $H_{1}$ is the distance from the center of the jth ellipse to the origin.
Substituting into (2.3) and (2.8) and evaluating the integrals, we find

$$
\begin{gather*}
\Phi(z)=q_{0} i \sum_{j=1}^{m}\left[\sqrt{l_{j}^{2}-\left(z-H_{j}\right)^{2}}+\sqrt{l_{j}^{2}-\left(z+H_{j}\right)^{2}}+2 i z\right]  \tag{2.13}\\
\Psi^{\prime}(z)=q_{0} z \sum_{j=1}^{m} \frac{h_{j}}{l_{j}}\left[\frac{i\left(z+H_{j}\right)}{\sqrt{l_{j}^{2}-\left(z+H_{j}\right)^{2}}}+1\right]
\end{gather*}
$$

If $\ell_{1}=h_{j}$ we then obtain the solution of the problem for a half-plane reinforced by thin circular insertions of different radil along the $x$-axis.
3. A half-plane reinforced along the $x$-axis by thin rectangular insertions. Here it is first necessary to consider insertions of constant thickness $2 h_{3}^{\circ}$ with triangular tips of length $\ell$, and then, keeping the length of the insertion $2 h_{\text {, }}$ unchanged, to pass to the limit permitting $\ell$ to tend to zero. After evaluation we obtain

$$
\begin{gather*}
\Phi(z)=\frac{q_{0}}{\pi} \sum_{j=1}^{m} h_{j}{ }^{0} \ln \frac{\tau_{1}{ }^{2}-1}{\tau_{2 j}{ }^{2}-1}, \quad \tau_{1 j}=\frac{z+h_{j}}{H_{j}} \\
\Psi(z)=\frac{4 q_{0}}{\pi} z \sum_{j=1}^{m} h_{j} h_{j}\left[\left(H_{j}+z\right)^{2}-h_{j}{ }^{2}\right]^{-1}, \quad \tau_{2 j}=\frac{z-h_{j}}{H_{j}} \tag{2.14}
\end{gather*}
$$

where $H_{3}$ are the distances of the centers of the insertions from the origin.
3. Effeot of a wodge and stamp on helf-plane. Let a thin smooth wedge of given shape which is symmetrical relative to the $x$-axis act on the $L_{x}$ portion of the $x$-axis in the $x \geq 0$ half-plane, and a system of smooth stamps of given shape symmetrical relative to the origin, on the $L_{y}$ portion of the $y$-axis.

According to (2.3) and (2.8)

$$
\begin{equation*}
\Phi^{\prime}(z)=\frac{2 q_{0}}{\pi} \int_{L_{x}} \frac{x v_{x}^{\prime} d x}{x^{2}-z^{z}}, \Psi^{\prime}(z)=-\frac{2 q_{0}}{\pi} \int_{L_{x}} \frac{x v_{x}^{\prime} d x}{(x+z)^{2}}-\frac{1}{\pi i} \int_{L_{u}} \frac{\rho(t) d t}{t-z} \tag{3.1}
\end{equation*}
$$

Here the second member in (2.8) has been rewritten in another form by using the variable $t=t y$; $L_{y}^{\prime}$ is traversed in the positive direction, and $p(t)$ is the pressure under the stamp.

On the $y$-axis we have

$$
\begin{equation*}
\tau_{x y}=0, \quad \operatorname{Re} i \Phi^{\prime}=0 \tag{3.2}
\end{equation*}
$$

Hence, from the second relationship (1.3) we deduce the pressure on the section

$$
\begin{equation*}
\operatorname{Re} i \Psi^{\prime}=q_{0} u_{y}^{\prime} \tag{3.3}
\end{equation*}
$$

where $u_{y}{ }^{\prime}$ is known. Therefore, substituting the value of $\psi^{\prime}$ from (3.1), we find

$$
\begin{equation*}
-\frac{1}{\pi} \int_{L_{y}^{\prime}} \frac{p(t) d t}{t-t_{0}}=q_{0} u_{v}^{\prime}+\frac{4 q_{0} y_{0}}{\pi} \int_{L_{x}} \frac{v_{x}^{\prime} x^{2} d x}{\left(x^{2}+y_{0}^{2}\right)^{2}} \tag{3.4}
\end{equation*}
$$

or, returning to the variable $y$

$$
\begin{equation*}
\frac{1}{\pi} \int_{L_{\nu}} \frac{p(y) d y}{y-y_{0}}=q_{0} u_{y}^{\prime}+\frac{4 q_{0} y_{0}}{\pi} \int_{L_{x}} \frac{x^{2} v_{x}^{\prime} d x}{\left(x^{2}+y_{0}{ }^{2}\right)^{2}} \quad\left(L_{\nu}=-L_{u}{ }^{\prime}\right) \tag{3.5}
\end{equation*}
$$

As an example, let us consider the simplest problem of a rectangular wedge and rectilinear stamp acting on an elastic half-plane.

If the wedge of thickness $2 h$ penetrates a depth $H$, then by first writing the integral in the right side of $(3.5)$ for a rectilinear wedge with a triangular tip of length $\ell$ and then passing to the limit as $\ell$ tends to zero, we may write taking into account that $u^{\prime}=0$

$$
\begin{equation*}
\int_{-b}^{b} \frac{p d y}{y-y_{0}}=-\frac{4 h q_{0} H^{2} y_{0}}{\left(H^{2}+y_{0}^{2}\right)^{2}} \tag{3.6}
\end{equation*}
$$

Here $b$ is the half-width of the portion of the stamp in contact with the half-plane.

The most general solution of (3.6) is [2]

$$
\begin{equation*}
p\left(y_{0}\right)=\frac{4 h q_{0} H^{2}}{\pi^{2} \sqrt{\overline{b^{2}}-y_{0}{ }^{2}}} \int_{-b}^{b} \frac{y \sqrt{b^{2}-y^{2}} d y}{\left(y^{2}+H^{2}\right)^{2}\left(y-y_{0}\right)}+\frac{P_{0}}{\pi \sqrt{\overline{b^{2}-y_{0}{ }^{2}}}} \tag{3.7}
\end{equation*}
$$

Here $P_{0}$ is the force pressing the stamp to the half-plane. The integral in the first term can be evaluated. We obtain
$p\left(y_{0}\right)=\frac{2 q_{0} h H}{\pi \Delta \sqrt{b^{2}-y_{0}{ }^{2}}} \frac{b^{2} H^{2}-\left(H^{2}+\Delta^{2}\right) y_{0}^{2}}{\left(y_{0}^{2}+H^{2}\right)^{2}}+\frac{P_{0}}{\pi \sqrt{b^{2}-y_{0}{ }^{2}}} \quad\left(\Delta=\sqrt{b^{2}+H^{2}}\right)$
Formula (3.8) is valid if

$$
\begin{equation*}
P_{0}>2 q_{0} h b^{2} H \Delta^{-3} \tag{3.9}
\end{equation*}
$$

The edges of the stamp will hence come in contact with the half-plane.
If (3.9) is not satisfied, then $p(b)=0$. Hence

$$
\begin{equation*}
P_{0}=2 q_{0} h b^{2} H \Delta^{-3} \tag{3.10}
\end{equation*}
$$

Substituting into (3.8) and computing, we obtain

$$
\begin{equation*}
p\left(y_{0}\right)=\frac{2 q_{0} h H}{\pi \Delta^{3}} \frac{\left[H^{2}\left(H^{2} \dot{-} \Delta^{2}\right)-b^{2} y_{0}^{2}\right] \sqrt{b^{2}-y_{0}^{2}}}{\left(y_{0}^{2}+H^{2}\right)^{2}} \tag{3.11}
\end{equation*}
$$

For a specified value of $P_{0}$ the relationship (3.10) determines the size of the pressure section. The possibility of solving (3.11) for a rectilinear stamp is stipulated by the bulging of the half-plane boundary in the neighborhood of the origin under the influence of the penetrated wedge.

If a semi-infinite rectangular wedge is driven in to the right along the $x$-axis in the half-plane so that the distance between its tip and the boundary of the half-plane is $H$, then the plus sign must be taken in the righthand side of (3.6) and we obtain for this case

$$
\begin{equation*}
p\left(y_{0}\right)=-\frac{2 q_{0} h I}{\pi \Delta \sqrt{b^{2}-y_{0}^{2}}} \frac{b^{2} H^{2}-\left(H^{2}+\Delta^{2}\right) y_{0}{ }^{2}}{\left(y_{0}^{2}+H^{2}\right)^{2}}+\frac{P_{0}}{\pi \sqrt{b^{2}-y_{0}^{2}}} \tag{3.12}
\end{equation*}
$$

The pressure $p(y)$ turns cut to be positive alon the whole stamp under the condition $\quad P_{0}>2 q_{0} h b^{2} H^{-1} \Delta^{-1}$

In the opposite case the pressure domain consists of the sections ( $a, b$ ), $(-b,-a)$. Hence $p( \pm a)=0$.

It is simplest to investigate this case by rewriting (3.0) as

$$
\begin{equation*}
\int_{a}^{b} \frac{p d y}{y^{2}-y_{0}^{2}}=\frac{2 h q_{0} / I^{2}}{\left(H^{2}+y_{0}^{2}\right)^{2}} \tag{3.14}
\end{equation*}
$$

Substituting $y^{2}=\xi, p_{1}(\xi)=p(\sqrt{\xi}) / 2 \sqrt{\xi}$, we write

$$
\begin{equation*}
\int_{a^{2}}^{b^{2}} \frac{p_{1}(\xi) d \xi}{\xi-\xi_{0}}=\frac{2 h q_{0} H^{2}}{\left(\xi_{0}+H^{2}\right)^{2}} \tag{3.15}
\end{equation*}
$$

Hence

$$
\begin{equation*}
p_{1}\left(\xi_{0}\right)=-\frac{h q_{0} H^{2}}{\pi^{2}}\left(\frac{\xi_{0}-a^{2}}{b^{2}-\xi_{0}}\right)^{1 / 2} \int_{a^{2}}^{b^{2}}\left(\frac{b^{2}-\xi_{0}}{\xi-a^{2}}\right)^{1 / 3} \frac{d \xi}{\left(\xi^{2}+H^{2}\right)^{2}\left(\xi-\xi_{0}\right)} \tag{3.16}
\end{equation*}
$$

Evaluating the integral and returning to the old variable, we obtain

$$
\begin{gather*}
p\left(y_{0}\right)=\frac{2 h q_{0} H y_{0}}{\pi\left(y_{0}^{2}+H^{2}\right)^{2}}\left[1+\frac{b^{2}-a^{2}}{m_{1} \Delta^{2}}\left(\frac{1}{m_{1}+1}+\frac{y_{0}^{2}+H^{2}}{2 m_{1}^{2} \Delta^{2}}\right)\right]\left(\frac{y_{0}^{2}-a^{2}}{b^{2}-y_{0}^{2}}\right)^{1 / 2} \\
m_{1}^{2}=\frac{a+H}{b+H} \tag{3.17}
\end{gather*}
$$

Here under the radical we understand a branch which takes positive values on the upper edge of the slit $(a, b)$.

The force pressing the stamp to the half-plane is

$$
\begin{equation*}
P_{0}=\frac{2 h g_{0} H^{2}\left(b^{2}-a^{2}\right)}{\left(a^{2}+H^{2}\right)^{3 / 2} \Delta} \tag{3.18}
\end{equation*}
$$

If it has been given, then we find the size of the pressure section from the equality (3.18).

The existence of the solution (3.17) is here related to dropping of the half-plane boundary toward the wedge under the influence of the wedge. This drop, and in general, the change in the half-plane boundary under the influence of the wedge is characterized exactly by the second member in (3.5). If the pressing force is not large enough, a gap will remain between the domain boundary and the stamp.

It is easy to write down the solution of (3.5) in the general case for any $u_{y}^{\prime}$ and $v_{x}^{\prime}$.

Let us note that for a given wedge there exists such a shape of a stamp (or stamps) for which the right-hand side of (3.5) vanishes. Namely, this will hold if

$$
\begin{equation*}
u_{y_{0}}^{\prime}=-\frac{4 y_{0}}{\pi} \int_{L_{x}} \frac{x^{2} v_{x}^{\prime} d x}{\left(x^{2}+y_{0}^{2}\right)^{2}} \tag{3.19}
\end{equation*}
$$

In this case, for example, for one stamp we will obtain

$$
\begin{equation*}
p\left(y_{0}\right)=\frac{P_{0}}{\pi \sqrt{b^{2}-y_{0}^{2}}} \tag{3.20}
\end{equation*}
$$

where $P_{0}$ is the force pressing the stamp. The stamp boundary, hence, turns out to be concave if the right side of (3.19) is positivc.

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